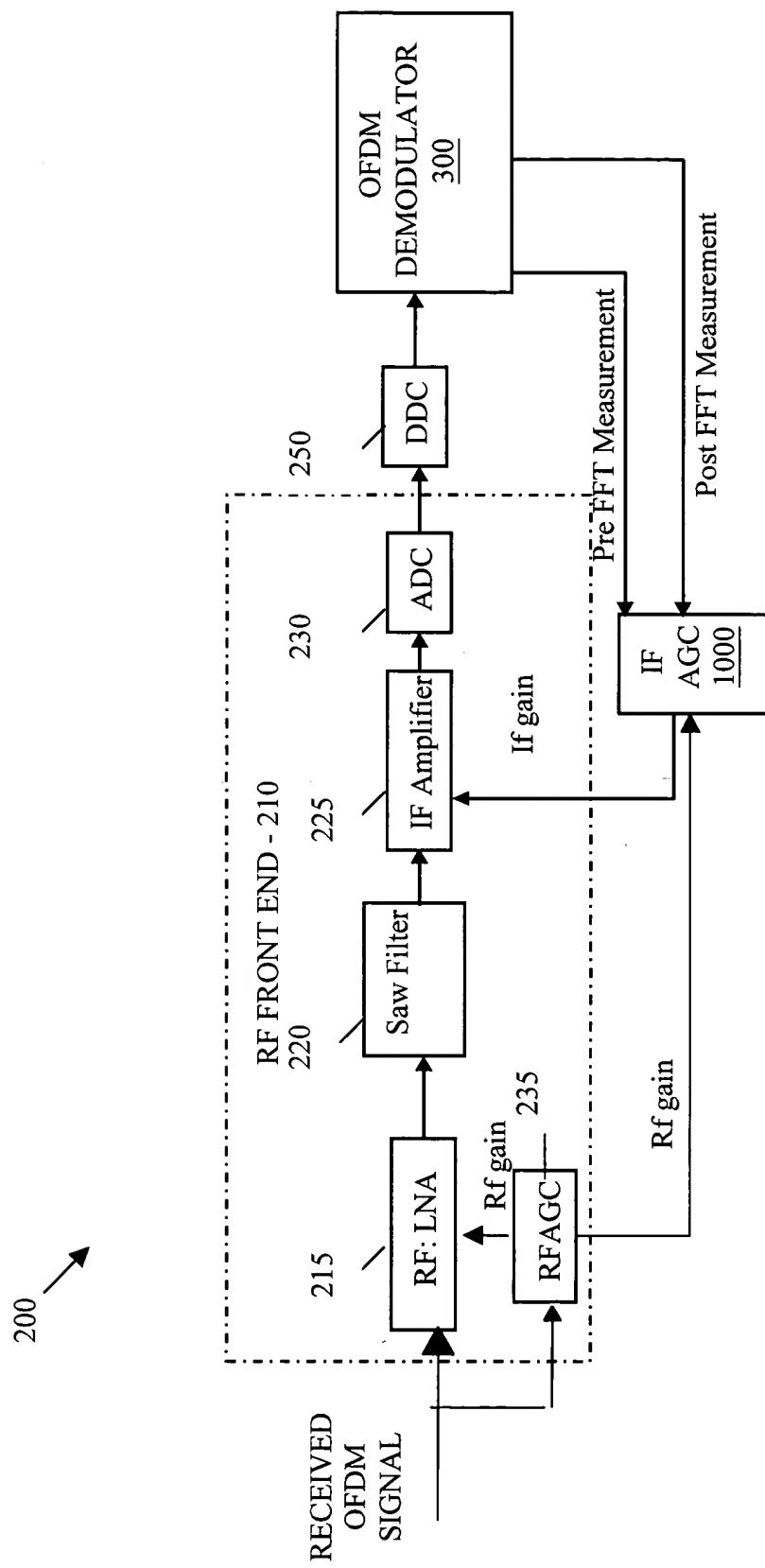


**FIG. 1**



**FIG. 2**

PRE-FFT MEASUREMENT

RECEIVED COMPLEX OFDM SAMPLES  
305

INTERPOLATION STAGE  
308

SYMBOL ROTATOR MODULE  
310

GI REMOVAL MODULE  
318

FFT  
325

UNUSED CARRIER REMOVAL  
350

DELETE/ ADD STAGE  
315

FINE CARRIER FREQUENCY OFFSET AND TIMING ESTIMATION ALGORITHM (GIB)  
320

COURSE CARRIER FREQUENCY OFFSET ALGORITHM (MODSC)  
700

TRACKSTAT\*  
ACQTIME

TIMING FSM  
400

TIMING ESTIMATES  
(tim0, tim1, timfull)

DIFFERENTIAL DEMODULATOR  
355

FREQUENCY DEINTERLEAVER  
360

QPSK DEMODULATOR  
365

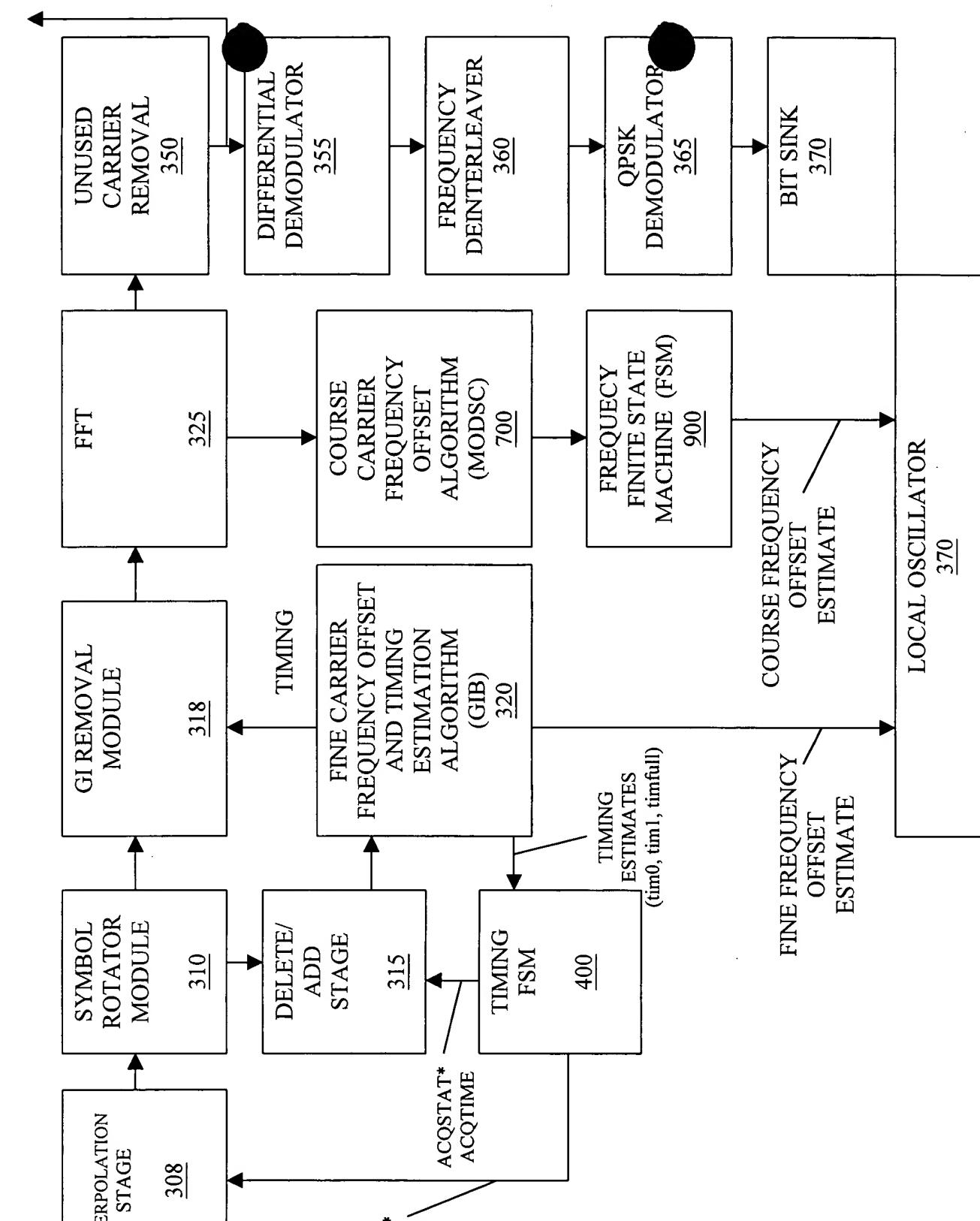
FREQUENCY FINITE STATE MACHINE (FSM)  
900

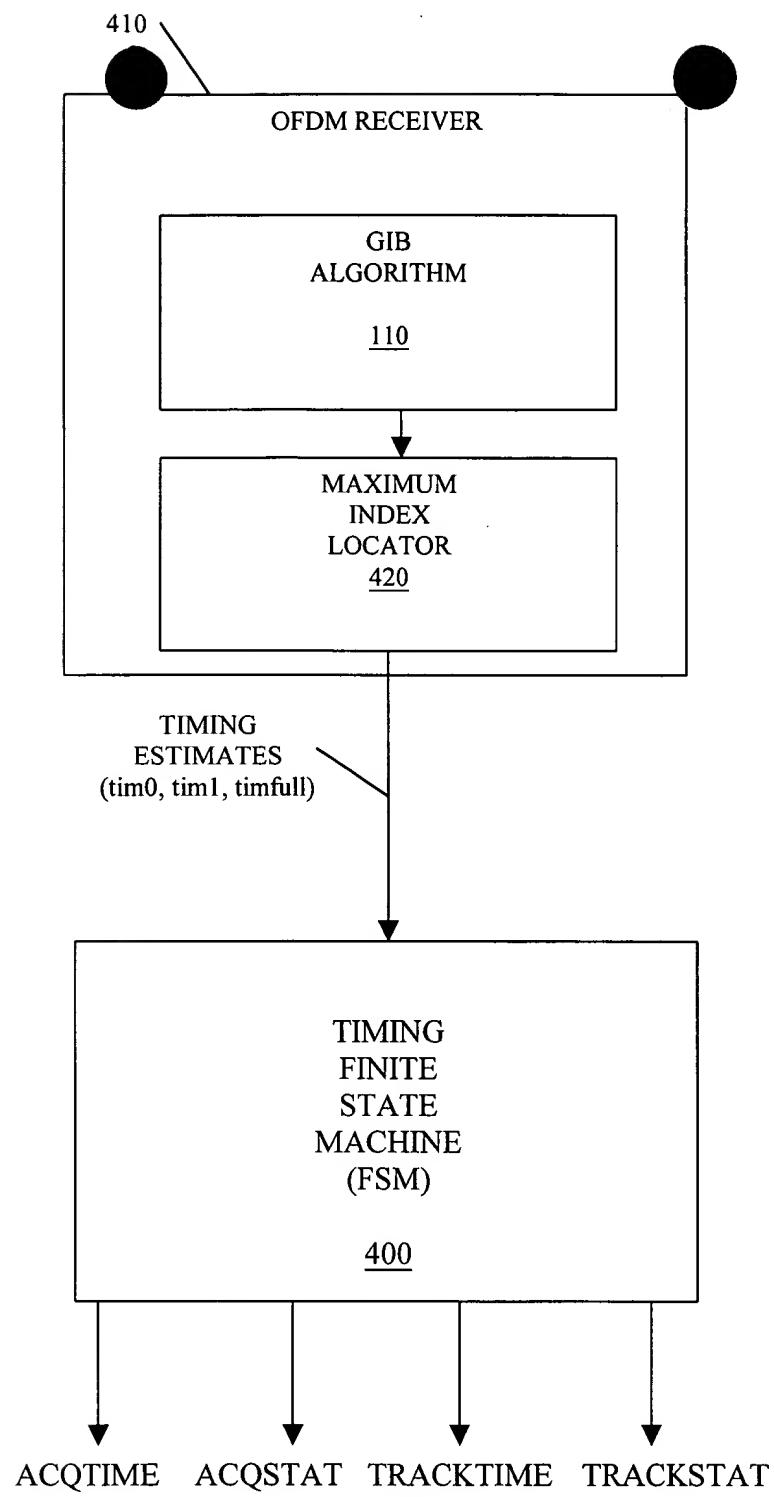
COURSE FREQUENCY OFFSET ESTIMATE

FINE FREQUENCY OFFSET ESTIMATE

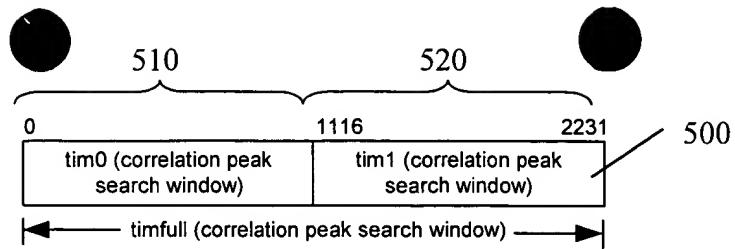
POST-FFT MEASUREMENT

FIG. 3

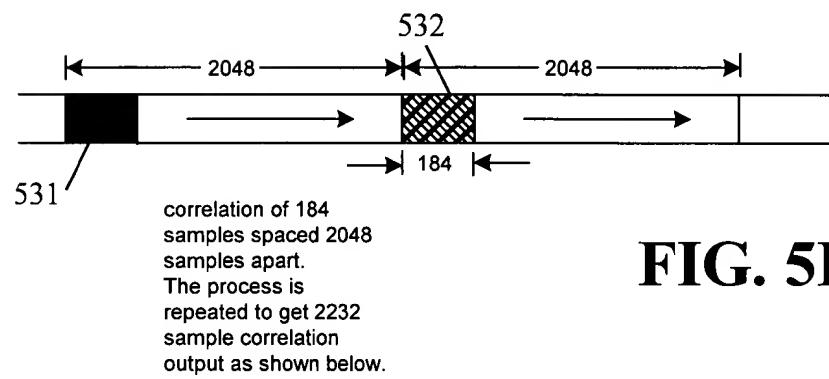




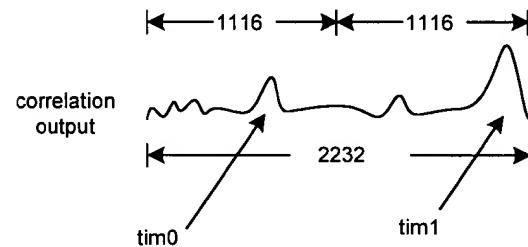
**FIG. 4**



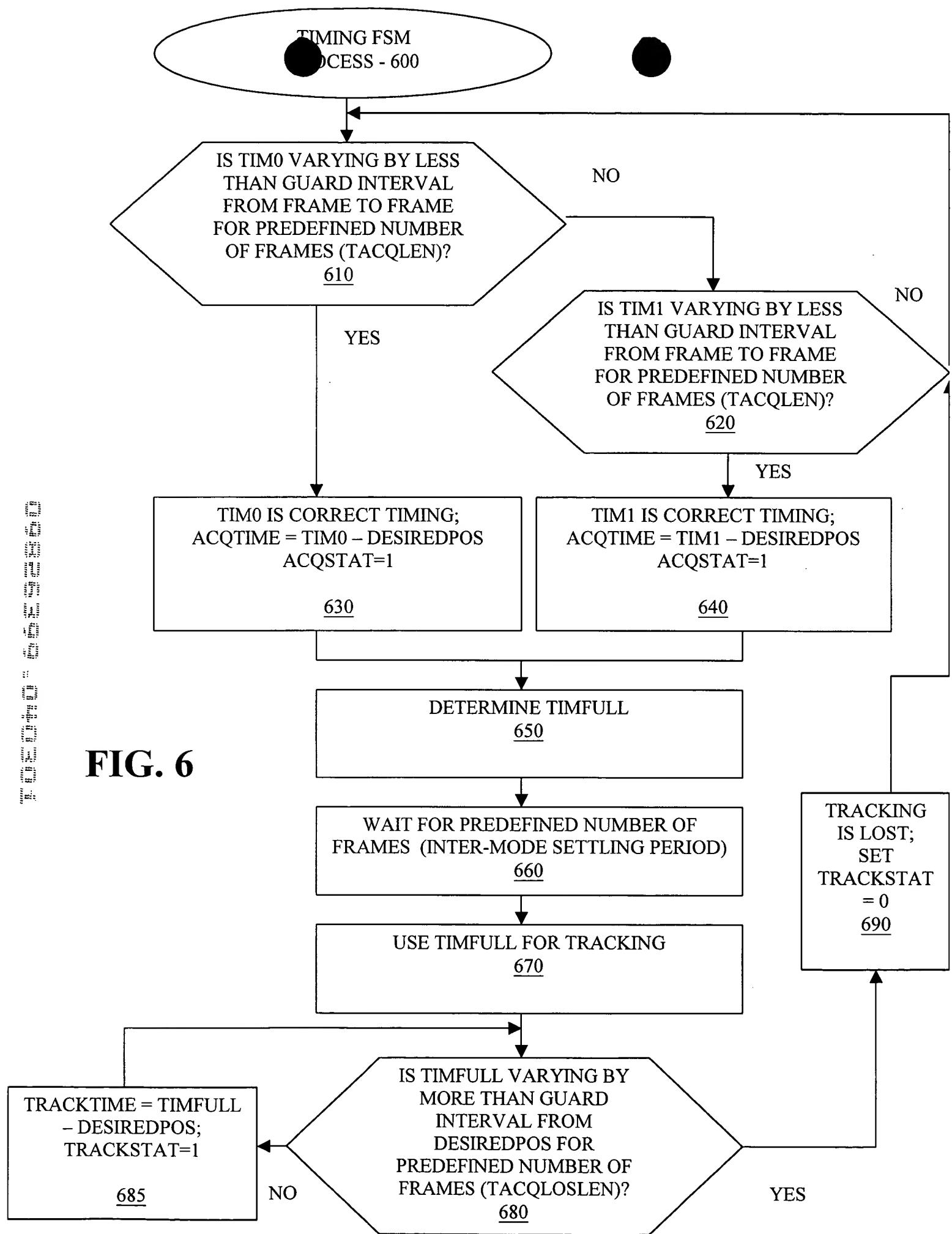
**FIG. 5A**



**FIG. 5B**



**FIG. 5C**



MODSC ALGORITHM - 700

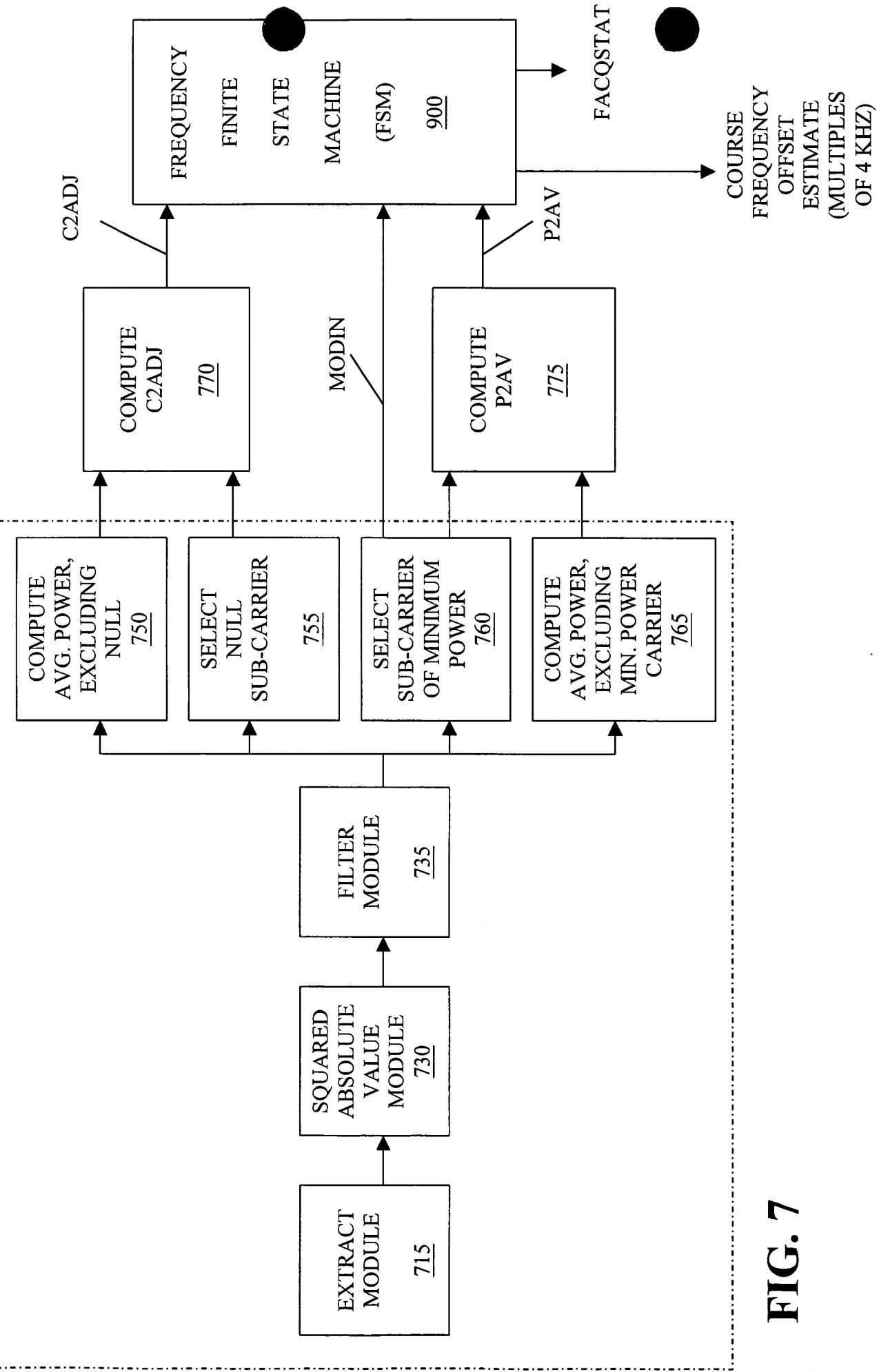
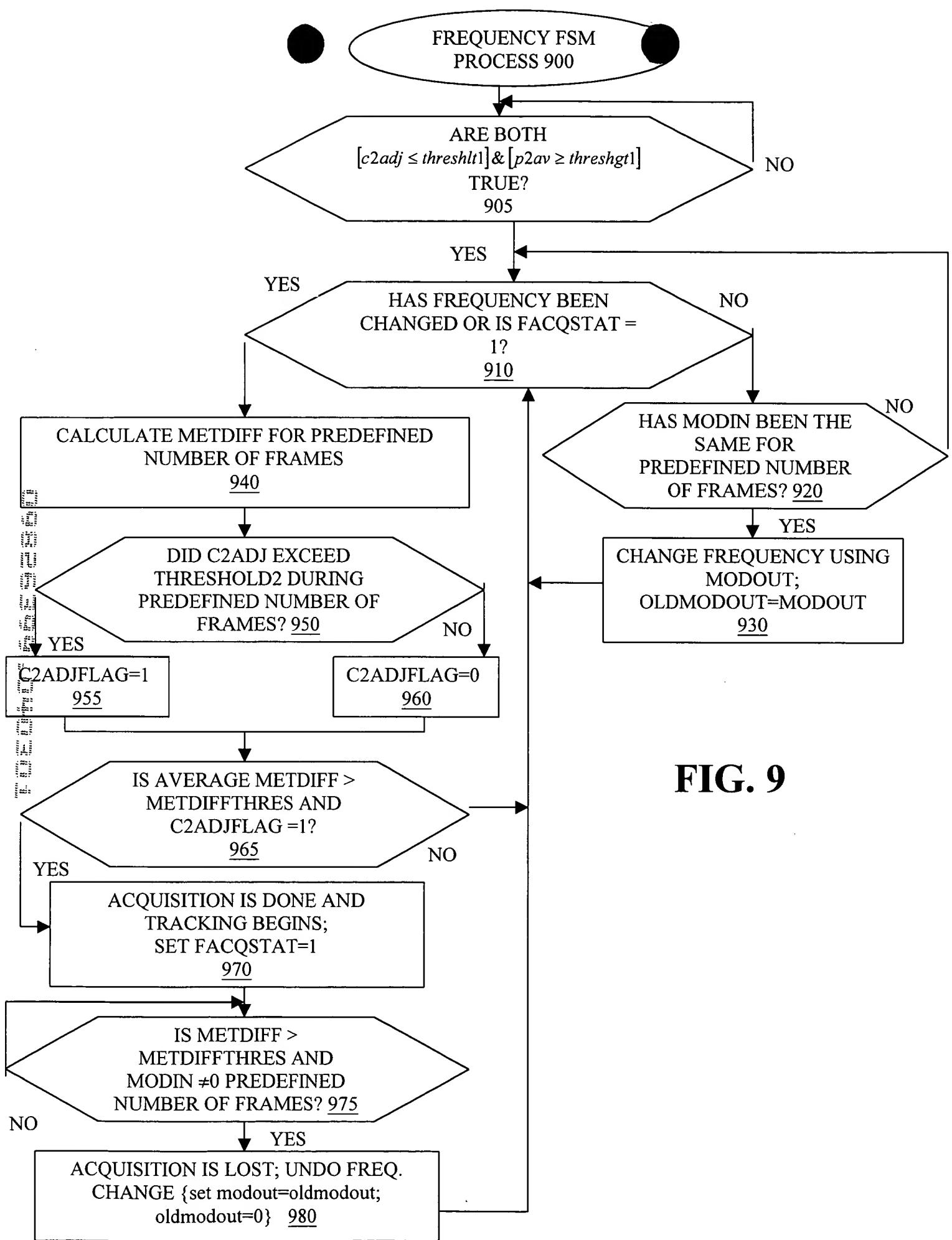
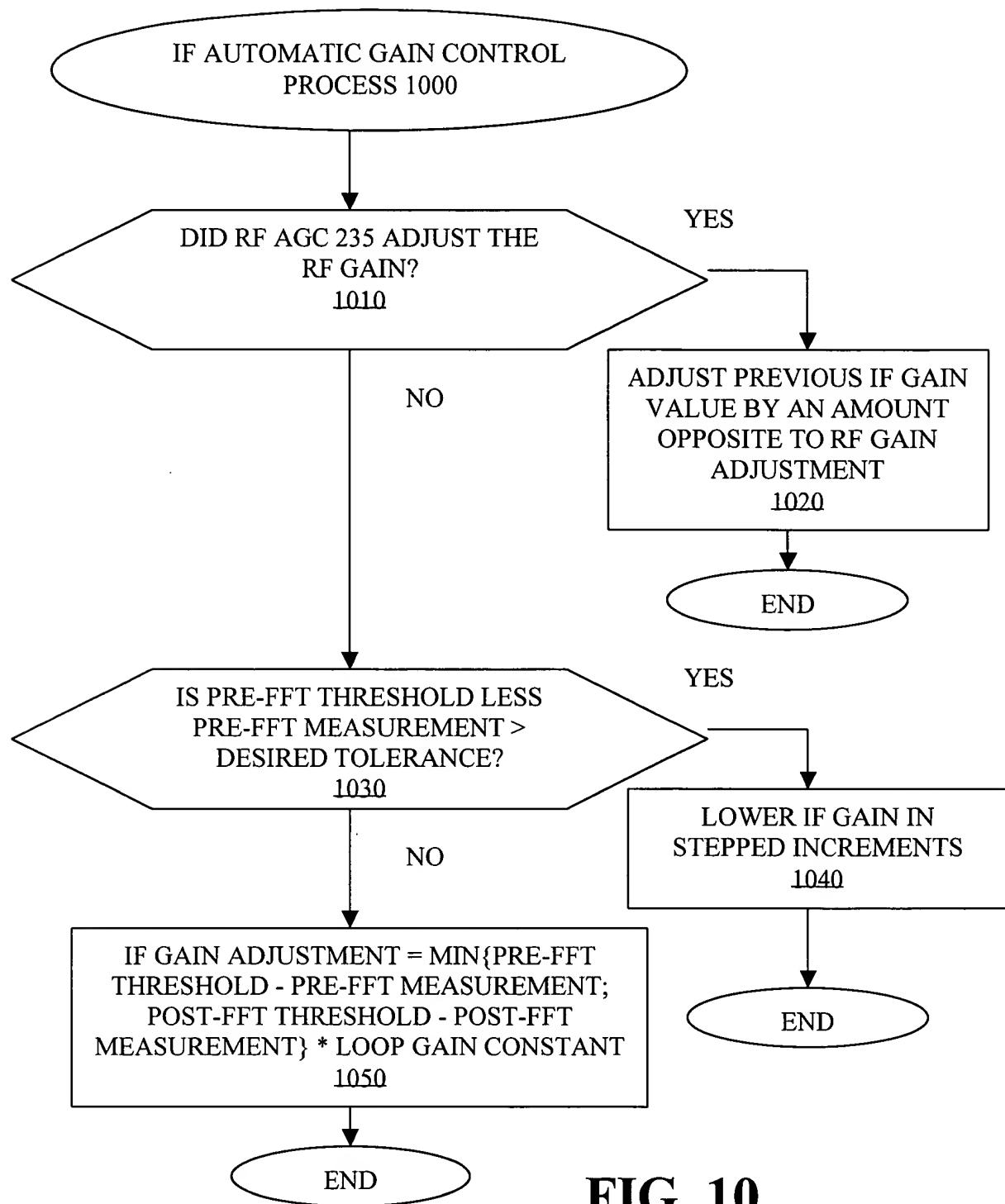


FIG. 7

0	1	18	2030	2047
zero carrier	positive carriers	unused carriers for MODSC		negative carriers

**FIG. 8**





**FIG. 10**

```

INPUT_PORT(1) register float *Prepower;
INPUT_PORT(2) register float *Postpower;
INPUT_PORT(3) register float *RFGain;
OUTPUT_PORT(1) register float *Output; /*IF AGC Gain in dB*/

BLOCKFACTOR long BlockFactor;

PARAMETER(1) float OutputIntervalWidth; /* 71 dB*/
PARAMETER(2) float SetPointdBPre; /*42.2*/
PARAMETER(3) float SetPointdBPost; /*32.2*/
PARAMETER(4) float KAGC; /*0.25*/
PARAMETER(5) float PreDropdB; /* 3.0*/
PARAMETER(6) long WaitTime; /*8 OFDM Frames!!*/

STATE float oldoutput;
STATE float oldrfgain;
STATE long counter;

#include <math.h>

void init ofdmagccontrol2()
{
/* initialize Sum */
oldoutput = 0.0;
counter = WaitTime;
}

void ofdmagccontrol2()
{
register float dbinpre, dbinpost, err, rfgain, output;
float HalfInterval = (OutputIntervalWidth / 2.0);

```

**FIG. 11A**

```

LOOP(BlockFactor)

printf("-----IFbeg-----\n");
dbinpre = *Prepower++; dbinpost = *Postpower++;
rfgain = *RFGain++;

printf("prepower = %f, post = %f, rfgain = %f\n", dbinpre, dbinpost, rfgain);
if((rfgain-oldrfgain)!=0.0)
{
    output = oldoutput -(rfgain-oldrfgain);
    printf("ifgain = -rfdiff = %f, oldrfgain = %f\n", output, oldrfgain);
}
else if ((SetPointdBPre-PreDropdB-dbinpre <=0.0)&& (counter >= WaitTime))
{
    output = oldoutput -(PreDropdB+2.0);
    printf("ifgain = due to Pre = %f\n", -PreDropdB);
    counter=0;
}
else
{
    counter++;
    if(SetPointdBPre-dbinpre < SetPointdBPost-dbinpost)
        err = SetPointdBPre - dbinpre;
    else
        err = SetPointdBPost-dbinpost;
    err = Kagc*err;
    output = oldoutput+err;
    printf("output = %f\n", output);
}

if(output>=HalfInterval)
    output = HalfInterval;
else if (output<=-HalfInterval)
    output = -HalfInterval;
else
    output = output;

*Output++ = output;
oldrfgain = rfgain;
oldoutput = output;
printf("-----IFend-----\n");
ENDLOOP
}

```

**FIG. 11B**